# JAKA間特卡

# JAKA Zu® 3 Cobot

Weight: 13.5 kg

Loading: 3 kg

Working radius: 587 mm

Repeatability: ±0.03 mm

### **Product Features**

- Flexible and light
- Small space requirement
- High Cost-effective

# **Recommended Markets**

3C electronics, Medical treatments, scientific researches, Injection molding

















Wireless connection No need oftraditional teaching device

Safety collaboration Graphic programming Built-in torque feedback detection

Easy use for zero basis

**Open Cooperation** Compatible with ROS operating system

**Integrated Joints** Easy to disassemble and transport

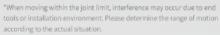
# **Technical Parameter**

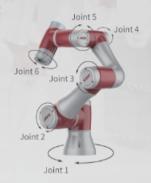
#### Character

Payload	3kg		
Weight (W cable)	13.5kg		
Work radius	587mm		
Repeatability	±0.03mm		
Axis	6		
Programming	graphical programming, free-drive		
Teach pendant	MT (PAD/Mobile) APP		
Collaborative operation	Accordance with GB11291.1-2011		
Power	200W		
Temperature range	0-50°C		
IP Specification	IP54		
Installation	Installation at any Angle		
Tool I/O	Digital input 2		
	Digital output 2		
	Analog input 1		
Tool I/O power	24V		
base diameter	129mm		
Materials	aluminum、PP		
Tool I/O size	M6		
Cable length	6 m		

#### Scope and speed \*

Robot		Work scope	Max speed
Joint 1		±270°	180°/s
Joint 2	17	-85°,+265°	180°/s
Joint 3		±175°	180°/s
Joint 4		-85°,+265°	180°/s
Joint 5		±270°	180°/s
Joint 6		±270°	180°/s
Max speed		/	1.5m/s

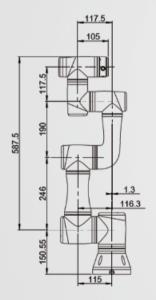




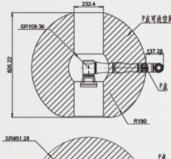
#### **Control Cabinet**

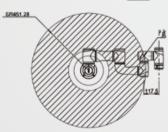
IP Specification	IP20		
Tool I/O	16 Digital input/16 Digital output /2 Analog input or output		
I/O Power	24V		
communication	TCP/IP,MODBUS TCP/RTU		
power	100-240VAC,50-60Hz		
size	400×230×260(mm) (W×H×D)	JAKA	
weight	15.5kg		
material	Stainless steel	-	

# JAKA Zu 3 Layout

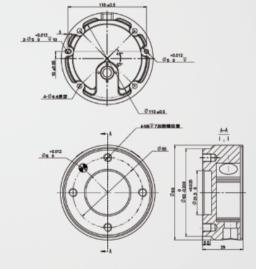


JAKA Zu 3 work radius





JAKA Zu 3 P point front view / top view



JAKA Zu 3 base / flange

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